

$$\eta^{00} = \eta^0_i \eta^0_j \eta_{ij}$$

$$= (-1)(-1) \eta_{00} = \eta_{00}$$

$$\hat{L}^{-1m}{}_{;j} \hat{L}^j{}_l = \delta^m_l$$

$$\begin{aligned} \uparrow \hat{L}^{-1m}{}_{;j} &= \eta_{mk} \hat{L}^i{}_k \hat{L}^j{}_i \\ &= \hat{L}^i{}_m \hat{L}^j{}_i \\ \hat{L}^{-1m}{}_{;j} &= \hat{L}^j{}_m \end{aligned}$$

$$X^i{}_i = \eta_{ij} \hat{L}^j{}_k \underline{X^k}$$

$$= \sum_{i,j} y_{ij} L_{ij} \sum_{k,m} X_{km}$$

$$= \sum_i L_i \sum_m X_{im}$$

$$= \sum_i \left[ \sum_m L_{im} \right] X_{im}$$

$$\begin{aligned} \sum_i X_i^c \sum_j y_j^i &= \sum_i \left[ \sum_m L_{im} \right] \sum_j L_{ij} X_j^i \\ &= \sum_i \left[ \sum_m L_{im} \right] \sum_j L_{ij} y_{jm} X_j^i \\ &= \sum_j \sum_m y_{jm} X_j^i = \sum_j X_j^i y_j^i \end{aligned}$$

$$\sum_j X_j^i = \sum_j y_j^i$$

$$\sum_j X_j^i \neq \sum_j y_j^i$$

$L^{-1} x' = x$

$$P = L^{-1} x' = x$$

$$\frac{\partial}{\partial x^i} = \partial_i$$

$$\frac{\partial}{\partial x^i} = \frac{\partial x^k}{\partial x^i} \frac{\partial}{\partial x^k}$$

$$= L^{-1 k}_i \partial_k$$

$$M^{\dots k} \checkmark \dots \checkmark \dots$$

$$= M^{\dots i} L^{\star}_i L^{-1 j} \checkmark \dots \checkmark \dots$$

$$= M^{\dots i} L^{-1 j}_i L^{\star}_j \checkmark \dots \checkmark \dots$$

$$= M^{i'j'} g_{ij} V_{i'j'}$$

$$= M^{i'j'} V_{i'j'}$$


---

$\sum_{k=0}^3 K^k$  is invariant

time  $d\tau$  in rest frame

$$d\tau = \sqrt{1 - \frac{v^2}{c^2}} dt$$

$\uparrow$   
 lab time

$$A'(x) = A(x) + g(x) \cdot \sqrt{x}$$

(local symmetry)

$$\psi'(x) = e^{i\alpha(x)} \psi(x)$$

charge

$$\left[ (\partial_i + iA_i) \psi \right]$$

$$= \partial_i \left[ e^{i\alpha} \psi \right]$$

$$+ iA_i (1 + g \partial_i \alpha) \psi$$

$$= e^{i\alpha} \partial_i \psi + (\cancel{i \partial_i \alpha} g) \psi$$

$$+iA, \cancel{e^{iqd}} \psi$$

$$= e^{iqd} [2i + Ai]$$

$$(D_i \psi)' = e^{iqd} D_i \psi$$

$$\psi' = e^{iqd} \psi$$

$$(D_i \psi)^* D_i \psi \text{ invariant}$$

$$\psi^* \psi \quad \parallel$$

$$D_i A_k = \underline{2A_k}$$

$\dots \partial x_j$

$$\partial^j A_k = \frac{\partial A_k}{\partial x_j}$$

$A^i$  contravariant

$\partial_i$  covariant

$A_i$

$\partial^i$   
 ~~$A^i$~~



$$du \wedge dv = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} dx \wedge dy$$