

Let's now compute the functional derivative of the action (15.2), which involves the square of the time-derivative  $\dot{q}(t)$  and the potential energy  $V(q(t))$

$$\begin{aligned}\delta S[q][h] &= \left. \frac{d}{d\epsilon} S[q + \epsilon h] \right|_{\epsilon=0} \\ &= \left. \frac{d}{d\epsilon} \int dt \left[ \frac{m}{2} (\dot{q}(t) + \epsilon \dot{h}(t))^2 - V(q(t) + \epsilon h(t)) \right] \right|_{\epsilon=0} \\ &= \int dt [m\dot{q}(t)\dot{h}(t) - V'(q(t))h(t)] \\ &= \int dt [-m\ddot{q}(t) - V'(q(t))] h(t)\end{aligned}\quad (15.11)$$

where we once again have integrated by parts and used suitable boundary conditions to drop the surface terms. In physics notation, this is

$$\frac{\delta S[q]}{\delta q(t)} = \int dt' [-m\ddot{q}(t') - V'(q(t'))] \delta(t' - t) = -m\ddot{q}(t) - V'(q(t)). \quad (15.12)$$

In these terms, the stationarity of the action  $S[q]$  is the vanishing of its functional derivative either in the form

$$\delta S[q][h] = 0 \quad (15.13)$$

for arbitrary functions  $h(t)$  (that **vanish at the end points of the interval**) or equivalently in the form

$$\frac{\delta S[q]}{\delta q(t)} = 0 \quad (15.14)$$

which is Lagrange's equation of motion

$$m\ddot{q}(t) = -V'(q(t)). \quad (15.15)$$

Physicists also use the compact notation

$$\frac{\delta^2 Z[j]}{\delta j(y)\delta j(z)} \equiv \left. \frac{\partial^2 Z[j + \epsilon\delta_y + \epsilon'\delta_z]}{\partial\epsilon\partial\epsilon'} \right|_{\epsilon=\epsilon'=0} \quad (15.16)$$

in which  $\delta_y(x) = \delta(x - y)$  and  $\delta_z(x) = \delta(x - z)$ .

**Example 15.1** (Shortest Path is a Straight Line) On a plane, the length of the path  $(x, y(x))$  from  $(x_0, y_0)$  to  $(x_1, y_1)$  is

$$L[y] = \int_{x_0}^{x_1} \sqrt{dx^2 + dy^2} = \int_{x_0}^{x_1} \sqrt{1 + y'^2} dx. \quad (15.17)$$

The shortest path  $y(x)$  minimizes this length  $L[y]$ , so

$$\begin{aligned}\delta L[y][h] &= \left. \frac{d}{d\epsilon} L[y + \epsilon h] \right|_{\epsilon=0} = \left. \frac{d}{d\epsilon} \int_{x_0}^{x_1} \sqrt{1 + (y' + \epsilon h')^2} dx \right|_{\epsilon=0} \\ &= \int_{x_0}^{x_1} \frac{y' h'}{\sqrt{1 + y'^2}} dx = - \int_{x_0}^{x_1} h \frac{d}{dx} \frac{y'}{\sqrt{1 + y'^2}} dx = 0\end{aligned}\quad (15.18)$$

since  $h(x_0) = h(x_1) = 0$ . This can vanish for arbitrary  $h(x)$  only if

$$\frac{d}{dx} \frac{y'}{\sqrt{1 + y'^2}} = 0\quad (15.19)$$

which implies  $y'' = 0$ . Thus  $y(x)$  is a straight line,  $y = mx + b$ .  $\square$

### 15.3 Higher-Order Functional Derivatives

The second functional derivative is

$$\delta^2 G[f][h] = \left. \frac{d^2}{d\epsilon^2} G[f + \epsilon h] \right|_{\epsilon=0}.\quad (15.20)$$

So if  $G_N[f]$  is the functional

$$G_N[f] = \int f^N(x) dx\quad (15.21)$$

then

$$\begin{aligned}\delta^2 G_N[f][h] &= \left. \frac{d^2}{d\epsilon^2} G_N[f + \epsilon h] \right|_{\epsilon=0} \\ &= \left. \frac{d^2}{d\epsilon^2} \int (f(x) + \epsilon h(x))^N dx \right|_{\epsilon=0} \\ &= \left. \frac{d^2}{d\epsilon^2} \int \binom{N}{2} \epsilon^2 h^2(x) f^{N-2}(x) dx \right|_{\epsilon=0} \\ &= N(N-1) \int f^{N-2}(x) h^2(x) dx.\end{aligned}\quad (15.22)$$

**Example 15.2** ( $\delta^2 S_0$ ) The second functional derivative of the action  $S_0[q]$  (15.1) is

$$\begin{aligned}\delta^2 S_0[q][h] &= \left. \frac{d^2}{d\epsilon^2} \int_{t_1}^{t_2} dt \frac{m}{2} \left( \frac{dq(t)}{dt} + \epsilon \frac{dh(t)}{dt} \right)^2 \right|_{\epsilon=0} \\ &= \int_{t_1}^{t_2} dt m \left( \frac{dh(t)}{dt} \right)^2 \geq 0\end{aligned}\quad (15.23)$$