Probability and Statistics

If we substitute our formula (13.169) for $\langle v^2(t) \rangle$ into the expression (13.123) for the acceleration of $\langle r^2 \rangle$, then we get

$$\frac{d^2 \langle \boldsymbol{r}^2(t) \rangle}{dt^2} = -\frac{1}{\tau} \frac{d \langle \boldsymbol{r}^2(t) \rangle}{dt} + 2e^{-2t/\tau} \langle \boldsymbol{v}^2(0) \rangle + \frac{6kT}{m} \left(1 - e^{-2t/\tau} \right). \quad (13.171)$$

The solution with both $\langle \mathbf{r}^2(0) \rangle = 0$ and $d \langle \mathbf{r}^2(0) \rangle / dt = 0$ is (exercise 13.21)

$$\langle \boldsymbol{r}^{2}(t) \rangle = \langle \boldsymbol{v}^{2}(0) \rangle \tau^{2} \left(1 - e^{-t/\tau} \right)^{2} - \frac{3kT}{m} \tau^{2} \left(1 - e^{-t/\tau} \right) \left(3 - e^{-t/\tau} \right) + \frac{6kT\tau}{m} t.$$
(13.172)

13.12 Characteristic and Moment-Generating Functions

The Fourier transform (3.9) of a probability distribution P(x) is its **characteristic function** $\tilde{P}(k)$ sometimes written as $\chi(k)$

$$\tilde{P}(k) \equiv \chi(k) \equiv E[e^{ikx}] = \int e^{ikx} P(x) \, dx. \tag{13.173}$$

The probability distribution P(x) is the inverse Fourier transform (3.9)

$$P(x) = \int e^{-ikx} \tilde{P}(k) \frac{dk}{2\pi}.$$
(13.174)

Example 13.10 (Gauss) The characteristic function of the gaussian

$$P_G(x,\mu,\sigma) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$
(13.175)

is by (3.18)

$$\tilde{P}_G(k,\mu,\sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int \exp\left(ikx - \frac{(x-\mu)^2}{2\sigma^2}\right) dx \qquad (13.176)$$
$$= \frac{e^{ik\mu}}{\sigma\sqrt{2\pi}} \int \exp\left(ikx - \frac{x^2}{2\sigma^2}\right) dx = \exp\left(i\mu k - \frac{1}{2}\sigma^2 k^2\right).$$

For a discrete probability distribution P_n the characteristic function is

$$\chi(k) \equiv E[e^{ikx}] = \sum_{n} e^{ikx_n} P_n.$$
(13.177)

The normalization of both continuous and discrete probability distributions implies that their characteristic functions satisfy $\tilde{P}(0) = \chi(0) = 1$.

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