1.20 Determinants

Often one uses the notation $|A| = \det A$ to denote a determinant. In this more compact notation, the obvious generalization of the product rule is

$$|ABC...Z| = |A||B|...|Z|.$$
 (1.207)

The product rule (1.204) implies that det (A^{-1}) is $1/\det A$ since

$$1 = \det I = \det (AA^{-1}) = \det A \det (A^{-1}).$$
 (1.208)

Example 1.28 (Derivative of the logarithm of a determinant) We see from our formula (1.195) for det A that its derivative with respect to any given element A_{ik} is the corresponding cofactor C_{ik}

$$\frac{\partial \det A}{\partial A_{ik}} = C_{ik} \tag{1.209}$$

since the cofactors C_{ij} and C_{jk} for all j are independent of A_{ik} . Thus the derivative of the logarithm of this determinant with respect to any parameter β is

$$\frac{\partial \ln \det A}{\partial \beta} = \frac{1}{\det A} \sum_{ik} \frac{\partial \det A}{\partial A_{ik}} \frac{\partial A_{ik}}{\partial \beta} = \sum_{ik} \frac{C_{ik}}{\det A} \frac{\partial A_{ik}}{\partial \beta}$$
$$= \sum_{ik} A_{ki}^{-1} \frac{\partial A_{ik}}{\partial \beta} = \operatorname{Tr} \left(A^{-1} \frac{\partial A}{\partial \beta} \right).$$
(1.210)

Incidentally, Gauss, Jordan, and modern mathematicians have developed much faster ways of computing determinants and matrix inverses than those (1.183 & 1.197) due to Laplace. Sage, Octave, Matlab, Maple, Mathematica, and Python use these modern techniques, which also are freely available as programs in C and FORTRAN from www.netlib.org/lapack.

Example 1.29 (Numerical Tricks) Adding multiples of rows to other rows does not change the value of a determinant, and interchanging two rows only changes a determinant by a minus sign. So we can use these operations, which leave determinants invariant, to make a matrix **upper triangular**, a form in which its determinant is just the product of the factors on its diagonal. For instance, to make the matrix

$$A = \begin{pmatrix} 1 & 2 & 1 \\ -2 & -6 & 3 \\ 4 & 2 & -5 \end{pmatrix}$$
(1.211)